
Ndrive V11 Pna UPDATED

the ndrive is a linear stepper motor with a single closed-loop position feedback controller, with a built-in encoder that acts as the input and output sensing device for the controller. the ndrive is a software-controlled stepper motor with no moving parts, providing for an extremely low-cost, low-friction drive solution. the ndrive hle drive series offers the highest level of encoder interpolation. this drive is designed for highly accurate experiments where encoder resolution and interpolation is important. the drive has a built-in encoder that is self-calibrating and is capable of performing in the full range of detected encoder signals. the ndrive family is capable of controlling a wide range of motors. the ndrive v11 pna is an ideal drive for future experiments requiring high precision, high velocity control over a large range of motor sizes. it can also be used as a high-performance, motor-based controller for human studies, such as the study of the benefits of limb stimulation for people with paralysis. the ndrive v11 pna has a maximum velocity of 19,000 rpm, an accuracy of $\pm 0.001\%$, and a 5-volt working voltage of 0.3 to 1.2 volts. the max output current is 18 milliamps (ma). the drive is designed for applications up to 100-watts. the drive is operated using a microcontroller or motor controller or direct interface using a serial port. the ndrive v11 pna is compatible with the neuronx protocol. step 3 mount the ndrive amplifier on a stereotaxic frame. connect the amplifier output to the ndrive base. the output of the amplifier is a differential signal that is compatible with all ndrives. mount the ndrive base on the ndrive amplifier. connect the ndrive base output to the computer via a patch cord. power the computer, amplifier, and ndrive base using a power supply. note: apply cement to only the ndrive base, leaving room to access the screw to release the ndrive unit after the experiment. do not cement the ndrive base to the ndrive amplifier. step 4 install the motor controller to the ndrive base. connect the motor output of the motor controller to the ndrive base output. connect the motor input of the motor controller to the computer via a patch cord. power the motor controller and computer using a power supply. note: apply cement to only the motor controller, leaving room to access the screw to release the motor controller after the experiment. do not cement the motor controller to the ndrive base.



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